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ROUGH SET THEORY FOR TOPOLOGICAL SPACES WITH VARIABLE PRECISION

Abdel Fatah A. Azzam

Department of Mathematics
Faculty of Science and Human Studies
Salman Bin Abdul-Aziz University
Al-Aflaj, 710-11912, SAUDI ARABIA
and
Faculty of Science
Tanta University
Tanta, EGYPT

Abstract: The topology induced by binary relations with variable precision is used to generalize the basic rough set concepts. The suggested topological structure opens up the way for applying a rich amount of topological facts and methods in the press of granular computing, in particular, the notion of topological membership functions is introduced that integrates the concepts of rough and fuzzy sets.

AMS Subject Classification: 06B30

Key Words: rough set, variable precision rough set model, α -lower approximation, topological space (TBS)

1. Introduction

The concept of topological space is a generalized structure used recently as a mathematical model for the analysis of information systems. The theory of rough sets provides a formal tool of dealing with incomplete information in terms of three valued logic, [5]. Many works have appeared recently, for example in structural analysis [6], in chemistry [16], and physics [3]. The purpose of

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the present work is to put a starting point for the applications of the abstract topological theory into fuzzy set theory, granular computing and rough set analysis, the generalization of the approximation of an arbitrary subset of a universe by two definable subsets are called α -lower and α -upper approximations which corresponding to rough operators. This generalization leads to increasing the accuracy of approximations, see [2]. The fuzzy set theory appeared for the first time in 1965, in the famous paper by Zadeh [20]. Since then, a lot of fuzzy mathematics has been developed and applied to uncertainty reasoning. In this theory, concepts like fuzzy subset, and fuzzy equality are usually depending on the concept of numerical grads of membership. On the other hand, the rough set theory introduced by Pawlak in 1982 [15], is a mathematical tool that supports also the uncertainty reasoning but qualitatively, their relationships have been studied in [9, 11, 18, 19]. In this paper we will integrate these ideas in terms of the concepts in topology.

2. Basic Concepts

The motivation for rough set theory has come from the needs to represent subsets of a universe in terms of equivalence classes of a partition of the universe. The partition characterizes a topological space with variable precision α called α -approximation space $K(U, R, \alpha)$, where U is a set called the universe, R is an equivalence relation and α is an error ratio such that $0 \le \alpha < 0.5$, see [1, 14, 17]. The equivalence classes of R are also known as the granules, elementary sets or blacks; we will use $R_X \subseteq U$ to denote the equivalence class containing $x \in U$. In the α -approximation space, we consider two operators, the α -upper and α -lower approximations of subsets: Let

$$X \subseteq U$$
, $\bar{R}_{\alpha}X = \{x \in U; R_x \cap^{\alpha} X \neq \phi\}$,
 $\underline{R}_{\alpha}X = \{x \in U; R_x \subseteq^{\alpha} X \neq \phi\}$,
 $X \subseteq^{\alpha} Y \text{ iff } C(X,Y) < \alpha$,

where

$$C(X,Y) = 1 - \frac{card\ (X \cap Y)}{card\ (X)} \ \text{if} \ card\ (X) > 0,$$

$$card\ (X,Y) = 0 \quad \text{if} \quad card\ (X) = 0,$$

where card denotes set cardinality and $0 \le \alpha \le 0.5$.

The α -Boundary, α -Positive and α -Negative regions are also defined:

$$BN_{\alpha}^{R}x = \bar{R}_{\alpha}x - \underline{R}_{\alpha}x,$$
$$pos_{\alpha}^{R}x = \underline{R}_{\alpha}x,$$
$$NEG_{\alpha}^{R}x = U - \bar{R}_{\alpha}X.$$

These notions can be also expressed by rough membership functions [17], namely,

$$\eta_{\alpha}^{R}X = \frac{|R_x \cap^{\alpha} X|}{|R_x|}, \quad x \in U.$$

Different values define boundary $(0 < \eta_{\alpha}^R x < 1)$, positive $(\eta_{\alpha}^R x = 1)$ and negative $(\eta_{\alpha}^R x = 0)$ regions, the membership function is a kind of conditional probability and its value can be interpreted as a degree of certainty to which x belongs to X with ratio α . A quotient set version is considered in [11, 13]. The Fuzzy Set [20] is a way to represent populations that set theory can not describe definitely. Fuzzy sets use a many-valued membership function, unlike the classical set theory which uses a two-valued membership function (i.e. an element is either in a set, or it is not). Let U denote a universal set and $A \subseteq U$. Then, a membership function on U, μ_A is a function such that $\mu_A : U \to L$ for some partially ordered set L.

L is usually a lattice [4]. Intuitively the membership function, μ_A , gives the degree to which an element $x \in U$ is in the fuzzy set A. In the case L is the closed interval [0,1], we call it the standard fuzzy set theory. A topological space [5] is a pair (U, τ) consisting of a set U, family τ of the subset of U satisfying the following conditions:

- i) $\phi \in \tau$ and $U \in \tau$.
- ii) τ is closed under arbitrary union.
- *iii*) τ is closed under finite intersection.

The pair (U, τ) is called a space, the elements of U are called points of the space, the subsets of U belonging to τ are called open sets in the space, and the complement of the subsets of U belonging to τ are called closed sets in the space; the family τ of open subsets of U is also called a topology for U.

It often happens that the open sets of space can be very complicated and yet they can all be described using a selection of fairly simple special ones. When this happens, the set of simple open sets is called a base or subbase (depending on how the description is to done). In addition, it is fortunate that many topological concepts can be characterized in terms of these simpler base

or subbase elements. Formally, a family $\beta \subseteq \tau$ is called a base for (U, τ) iff every non empty open subset of U can be represented as a union of subfamily of β . Clearly, a topological space can have many bases.

A family $S \subseteq \tau$ is called a subbase iff the family of all finite intersections is abase for (U, τ) . We have generalized the notion of α -lower approximation or α -positive region of the set $A \subseteq^{\alpha} U$ as,

$$A^0_{\alpha} = \bigcup \{G \cap A : C(G, A) \le \alpha, \quad G \text{ is open}\},$$

which is called the T-interior of a subset $A \subseteq U$. Note that A is open iff $A = A_{\alpha}^{0}$,

$$\bar{A}_{\alpha} = \bigcap \{ F \subseteq U : C(F, A) < 1 - \alpha, A \subseteq F, F \text{ is closed} \}$$

which is called T- closure of a subset $A \subseteq U$. Note that A is closed iff $A = \bar{A}_{\alpha}$.

$$A_{\alpha}^{b} = \bar{A}_{\alpha} - A_{\alpha}^{0}$$

is called the α -boundary region of a subset $A \subseteq^{\alpha} U$.

$$A_{\alpha}^{N} = U - \bar{A}_{\alpha}$$

is called the α -negative region of a subset $A \subseteq^{\alpha} U$.

3. Rough Set Theory in Topological Spaces with Variable Precision

The reference space in rough theory is the approximation space whose topology is generated by the equivalence classes of R. This topology belongs to a special class known by clopen topology, in which every open set is closed. Clopen topology is called quasi-discrete topology in digital geometry; Lin calls it Pawlak space [14]. Clopen topology is a kind of α -approximations that are transitive. It is too restrictive, for example, "East LA is close to LA, LA is close to West LA. However, East LA is not considered to be close to West LA", [14]; approximations are often not transitive. Lin [7, 8, 12] introduced a neighborhood system to handle such general situations. We will use topology; in other words, " α -approximation space" is a α topological space. We will express rough set properties in terms of topological concepts. Let X a subset. Let \bar{X}_{α} , X_{α}^{0} and X_{α}^{b} be α -closure, α -interior, and α -boundary points respectively, X is exact if $X_{\alpha}^{b} = \phi$, otherwise X is rough. It is clear that X is exact iff $\bar{X}_{\alpha} = X_{\alpha}^{0}$. In a Pawlak space a subset $X \subseteq U$ has the following types of definability:

1- X is totally definable if X is exact set $\bar{X}_{\alpha} = X = X^{0}$,

- 2- X is internally definable if $X = X_{\alpha}^{0}, X \neq \bar{X}_{\alpha}$,
- 3- X is externally definable if $X \neq X_{\alpha}^{0}, X = \bar{X}_{\alpha}$
- 4- X is undefinable if $X \neq X_{\alpha}^{0}, X \neq \bar{X}$.

Proposition 1. If A is an exact set in (U, τ, α) and $\tau \subset \tau'$, then A is exact with respect to τ' .

Proof. Since $BN_{\alpha}^{\tau}A \subset BN_{\alpha}^{\tau\prime}$ and $BN_{\alpha}^{\tau}A = \phi$. Then $BN_{\alpha}^{\tau\prime}A = \phi$ and A is exact. In other words, if A is τ -exact then A is τ -clopen and consequently, τ' -clopen. Hence A is τ' -exact. It is easy to have examples for a τ' -exact set which is not τ -exact. Let us observe that $\bar{A}^{\tau\prime} = \bar{A}^{\tau}$ iff $\bar{A}^{0\tau} = \bar{A}^{0\tau\prime}$. The following proposition gives the condition for τ' -exact sets to be τ -exact sets, $\tau \subset \tau'$.

Proposition 2. If (U, τ, α) is α - space and $\tau \subset \tau'$ then each exact set in τ' is exact set in τ iff $\bar{G}^{\tau}_{\alpha} = \bar{G}^{\tau'}_{\alpha} \forall G \in \tau'$.

Proof. If A is τ' -exact, then $\bar{A}^{\tau'} = A$ and $\bar{A}^{\tau} = A$, hence $\bar{A}^{\tau/}\bar{A}^{\tau}$. Conversely: if $\bar{A}^{\tau'} = \bar{A}^{\tau}$ and A is τ' -exact, then A is exact.

An original rough membership function is defined using equivalence classes. We will extend it to topological spaces. If τ is a topology on a finite set U, where its base is β , then the rough membership function with variable precision α is

$$\mu_{\alpha x}^{\tau} X \doteq \frac{|\{\cap B_x\} \cap X|}{|\cap B_x|}, B_x \in \beta$$

and $x \in U$, where B_x is any member of β containing x. It can be shown that this number is independent of the choice of bases. Since, the intersection of all members of the topology containing x concedes with the intersection of all members of a base containing x. Note that if the topology is the clopen one x belongs to a unique member of the base. Moreover the above membership function give the ordinary set theory if τ is discrete topology and rough set theory if τ is clopen (quasi discrete) topology.

The following example illustrates the above definition. Let

$$U = \{0, 1, 2, 3, 4, 5\}, \beta = \{\{2\}, \{3\}, \{0, 1, 2\}, \{2, 3, 4\}, \{3, 5\}\},$$

 $X = \{2, 4, 5\}$ and $\alpha = 0.5$ we get:

$$\mu_{0.5x}^{\tau}(0) = \frac{|\{0,1,2\} \cap^{0.5} \{2,4,5\}|}{|\{0,1,2\}|} = \frac{0}{3} = 0,$$

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$$\mu_{0.5x}^{\tau}(1) = 0, \quad \mu_{0.5x}^{\tau}(2) = 1, \quad \mu_{0.5x}^{\tau}(3) = 0, \quad \mu_{0.5x}^{\tau}(4) = \frac{2}{3},$$

$$\mu_{0.5x}^{\tau}(5) = \frac{1}{2}.$$

In the case of infinite universe, this membership function can be use for spaces having locally finite neighborhood systems in the sense that there are only finitely many minimal neighborhoods for each point. The rough membership functions allow us to express fuzzy theory in topological spaces: Let $X \subseteq U$ be a subset, we define a fuzzy set by using the rough membership function of topological spaces with variable precision α , $X_{\sim} = \{(x, \mu_{\alpha x}^{\tau}(x)) : \forall x \in U\}$. From the above example, we find that: if $X \doteq \{2, 4, 5\}$ then,

$$X_{\sim} = \{(0,0), (1,0), (2,1), (3,0), (4,\frac{2}{3}), (5,\frac{1}{2})\}.$$

4. Rough Set Theory in the Topology of Binary Relation

As we have pointed out earlier that Lin introduced the formalism of neighborhood system to handle such general situations. We will consider the topology generated from the binary relation R. If U is a finite universe and R is a binary relation on U, then we define, right neighborhood

$$xR=\{y:xRy\}.$$

We should note that xR is a right neighborhood of x, but xR is not necessary a right neighborhood of any element in xR. In fact, the set of all elements, each of which has xR as its right neighborhood, is called the center of xR. The collections of all centers form a partition of U; see [8] for details. We will not consider right neighborhood system (T.Y. Lin skips the word right), we will consider the topology generated by right neighborhoods. Taking such view xR is an open set, which as a neighborhood (in the sense of topological space) of each of its points. To construct the topology, we consider the family $S = \{xR : x \in U\}$ of right neighborhood as a subbase. Let the induced topology be τ . The family S as the subbase of τ will be denoted by $S_R = \{xR : x \in U\}$, and we write $S_x = \{G \in S_R : x \in G\}$. Since all finite intersections of members of a subbase form a base, the notion of topological rough membership functions can be expressed by subbase:

$$\mu_x^{\tau}(x) = \frac{|\{\cap S_x\} \cap X|}{|\cap S_x|}, \quad x \in S_x, \quad S_x \in S.$$

Note that this rough membership is very different from rough set theory or Lin's rough membership function of right neighborhood. In Lin's case instead of $\cap S_x$, he will use xR, which is unique; we will report the difference in future work. It may exists $y \in U$, and y belongs to more than one S_x as shown in the following example; note that one of S_x and xR is the same as sets. However, they are different xR is a right neighborhood and is unique (in the formalism of Lin's neighborhood system), while S_x is a set of open neighborhood of x in the topology τ .

Example 1. Let $U = \{0,1,2,3,4,5\}$, $0R = \{0,1,2\} = 1R$ $2R = 3R = \{2,3\}$, $4R = \{3,4\}$, $5R = \{5\}$, then

 $S = \{\{0, 1, 2\}, \{2, 3\}, \{3, 4\}, \{5\}\}\}$

$$\Rightarrow \beta = \{\{0, 1, 2\}, \{2, 3\}, \{3, 4\}, \{5\}, \{2\}, \{3\}\}\}$$

$$\Rightarrow \tau = \{U, \phi, \{0, 1, 2\}, \{2, 3\}, \{3, 4\}, \{5\}, \{2\}, \{3\}, \{0, 1, 2, 3\},$$

$$\{0, 1, 2, 3, 4\}, 0, 1, 2, 5\}, \{2, 3, 4\}, \{2, 3, 5\}, \{3, 4, 5\}, \{2, 5\}, \{3, 5\},$$

{2, 3, 4, 5}}.

Let $X = \{0, 1, 2, 3\}$; therefore

$$\begin{split} \mu_X^\tau(0) &= \frac{|\{0,1,2\} \cap \{2,3,1,0\}|}{|\{0,1,2\}|} = \frac{3}{3} = 1, \quad \mu_x^\tau(1) = 1, \quad \mu_x^\tau(2) = 1, \\ \mu_x^\tau(3) &= 1, \quad \mu_x^\tau(4) = \frac{1}{2}, \quad \mu_x^\tau(5) = 0. \end{split}$$

Then $X_{\sim} = \{(0,1), (1,1), (2,1), (3,1), (4,\frac{1}{2}), (5,0)\}.$

From the rough membership function with variable $\alpha = 0.5$, we get:

$$\underline{R}_{0.5}X=X_{0.5}^0=\{0,1,2,3\}, \overline{R}_{0.5}=\{0,1,2,3,4\}, NEG_{0.5}^R(X)=\{4,5\}$$
 and $BN_{0.5}^R(X)=\phi.$

We can get the interior and closure of X by using the definitions of τ -closure and τ -interior without using the membership function as follows: Here are the family F of all τ -closed sets:

$$F = \{\phi, U, \{3, 4, 5\}, \{0, 1, 4, 5\}, \{0, 1, 2, 5\}, \{0, 1, 2, 3, 4\}, \{0, 1, 3, 4, 5\}, \{0, 1, 2, 4, 5\}, \{4, 5\}, \{5\}, \{3, 4\}, \{0, 1, 5\}, \{0, 1, 4\}, \{0, 1, 2\}, \{0, 1, 3, 4\}, \{0, 1, 2, 4\}, \{0, 1\}\}.$$

So,

$$X_{0.5}^0 = \{0, 1, 2, 3\}, \overline{X}_{0.5} = \{0, 1, 2, 3, 4\}.$$

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5. Granular Structure in the Topology of Binary Relations

The purpose of this section is to investigate the knowledge representations and processing of binary relations in the style of rough set theory. Let us consider the pair (U, B), where $B = \{R_1, R_2, ..., R_n\}$ is a family of general binary relations on the universe U. When B is a family of equivalence relations, Pawlak call it knowledge base and Lin call the general case binary knowledge base in [8]. As the term "knowledge base" often means something else, Lin begin to use the generic name granular structure [8, 10]. We will use knowledge structure and granular structure interchangeably.

Next, we will consider the topological space for each binary relation; we will call it the topological space of the binary relation (TBS). We denote the base β_R that is generated by the binary relation R. Note that two distinct binary relation R and R' may generate the same topology as shown in the following example: Let $U = \{0, 1, 2, 3, 4, 5\}$, R and R' are distinct binary relations, where

$$R = \{(0,0), (0,1), (0,2), (1,2), (1,3), (2,2), (2,3), (3,2), (3,3), (4,3), (4,4), (5,5)\},$$

$$R' = \{(0,0), (0,1), (0,2), (1,0), (1,1), (1,2), (2,2), (2,3), (3,3), (4,3), (3,4), (4,4), (5,5)\}.$$

Their (right) neighborhood systems are (as subbases):

$$0R = \{0, 1, 2\}, \ 1R = 2R = 3R = \{2, 3\}, \ 4R = \{3, 4\}, \ 5R = \{5\},\$$

 $0R' = 1R' = \{0, 1, 2\}, 2R' = \{2, 3\}, 3R' = 4R' = \{3, 4\}, 5R' = \{5\}.$

These two subbases generated the same base $S_R = \{\{0,1,2\},\{2,3\},\{3,4\},\{5\}\}\} = S_{R'}$, hence the same topology $\tau_R = \tau_{R'}$.

Next, we will generalize the notion of reducts to TSB, the topological space of binary relations.

Defination 1. Let $P \subseteq B$ be a subset of B, $r \in p$, where B be a class of binary relations, r is said to be superfluous binary relation in P if: $\beta_P = \beta_{(P-\{r\})}$.

The set M is called a minimal reduct of P iff:

(i)
$$\beta_M = \beta_P$$
.

(ii)
$$\beta_M \neq \beta_{(P-\{r\})}, \forall r \in M$$
.

The following example illustrates the notion given above,

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Example 2. Let U = \{1, 2, 3, 4, 5\} and the 3 subbases S_r = \{\{1, 2\}, \{2, 3, 4\}, \{4, 5\}\}, S_P = \{\{1, 2, 3\}, \{3, 4\}, \{5\}\}, S_q = \{\{1, 2\}, \{3, 4\}, \{4, 5\}\}\}. Then we have a joint subbase S_B = \{\{1, 2\}, \{2, 3, 4\}, \{4, 5\}, \{1, 2, 3\}, \{3, 4\}, \{5\}\}\}. Next consider S_{(B-r)} = \{\{1, 2, 3\}, \{3, 4\}, \{5\}, \{1, 2\}, \{4, 5\}\}\}, \beta_{(B-r)} = \{\{1, 2\}, \{3\}, \{4\}, \{5\}\}, \{3, 4\}, \{5\}\}, S_{(B-P)} = \{\{1, 2\}, \{2\}, \{3, 4\}, \{4, 5\}, \{3, 4\}, \{5\}\}, S_{(B-q)} = \{\{1, 2\}, \{2\}, \{3, 4\}, \{4, 5\}, \{1, 2, 3\}, \{3, 4\}, \{5\}\}, S_{(B-q)} = \{\{1, 2\}, \{2\}, \{3\}, \{4\}, \{5\}\} = \beta_B. So we find that q is only superfluous relation in B, and we have RED(B) = \{r, p\}, CORE(B) = \{r, p\}.
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6. Conclusions

Topological generalization of rough sets and variable precision rough set model are applied together, to get a new approach for basic rough sets concepts. We believe that such generalized rough set theory will be useful in digital topology [4] as well as biomathematics [12]. Our approach in essence is to topologize information tables (also known as information systems). Our theory connects rough sets, topological spaces, fuzzy sets, and neighborhood systems (binary relations, pre-topology). This theory brings in all these techniques to information analysis and knowledge processing.

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